# JHU Sys5 Description

### 1 Abstract

JHU Sys5 utilized a fusion of one i-vector system and two x-vector systems, all trained on 16kHz microphone data. The i-vector system in the fusion was also submitted as Sys2, and one of the x-vector systems was submitted as Sys4. The other x-vector system was identical to Sys4, except with a 128-dimensional embedding. Marks from clustered segments were also refined with VB diarization. In Track 2, SAD marks were determined with a TDNN originally trained on 16kHz speech with augmentations, but with the final layer retrained on the dev data.

## 2 Data Resources

The SAD algorithm used audio from European Parliament videos. The clean, 16kHz microphone recordings were subsequently augmented with noise and music from the MUSAN corpus, and reverberated with impulse responses from the AIRS corpus.

The i-vector system (UBM,T) as well as the PLDA were trained with VoxCeleb only. All i-vectors, both in PLDA training and at test-time, were whitened with statistics from the aggregate of VoxCeleb, Mixer 4/5, and the DIHARD data.

The x-vector systems were trained with data from VoxCeleb, Mixer 4/5, speaker-labeled segments from numerous broadcast corpora (LDC: 97S44, 98S71, 98S73, 2009S02, 2012S06, 2013S02, 2013S04, 2013S07, 2013S08, 2014S07, 2014S09, 2015S01, 2015S06, 2015S11, 2015S13, 2016S01, 2016S03, 2016S07, 2017S02, 2017S15, 2017S25), and the same European Parliament audio used in the SAD training. The x-vector systems were trained in accordance with the SRE16 Kaldi recipe with embedding layers of either 128 or 256 dimensions. PLDA was trained with VoxCeleb only, and all x-vectors both in PLDA training and at test-time were whitened with statistics from the aggregate of VoxCeleb, Mixer 4/5, and the DIHARD data.

The UBM and T matrix used in the resegmentation algorithm was trained on VoxCeleb only.

## 3 Algorithm Details

#### 3.1 SAD

The SAD algorithm was a 5-layer TDNN with a final sigmoid layer and used log-compressed magnitudes from 35 mel filters as input. The first layer aggregated 5 frames (50ms) of context, and each subsequent layer doubled the width of a 3 tap filter, resulting, in the end, in +/- 640 ms of context at the final sigmoid layer. ReLU non-linearities were used between all layers (except the final sigmoid non-linearity). While the system was initially trained on the European Parliament audio (with a cross-entropy metric), the final layer was retrained using the DI-HARD dev data. Final output probabilities were smoothed with a 500ms median filter prior to thresholding at 0.50.

## 3.2 Segment Clustering

Speech was segmented into approximately 1.5 second windows with 0.75 second hops, 24 MFCCs were extracted every 10ms after a 3-second sliding mean subtraction (plus deltas for i-vectors), and i-vectors and both types of x-vectors were computed for each segment. These segment representations were scored with PLDA (trained with segments labeled only for speaker) within each representation type, and then the scores were fused with summation in the log space (weighted to optimize performance on the dev data). The fused scores were then clustered with AHC (average score combination at merges). The stopping threshold for merging was learned on the dev data and tuned to optimal DER.

### 3.3 Resegmentation

Resegmentation was performed with VB diarization <sup>1</sup>. The input features were 24 MFCCs computed every 10ms. The algorithm was initialized with the marks from clustering, then allowed to run only one pass with a downsample parameter of 3.

<sup>&</sup>lt;sup>1</sup>http://speech.fit.vutbr.cz/software/vb-diarization-eigenvoice-and-hmm-priors

## 4 System Requirements

- The i-vector training was distributed across numerous CPUs, determined by a grid scheduler with no concern for CPU specifics.
- The x-vector training was distributed across numerous GPUs, in accordance with the linked Kaldi recipe.
- The SAD system was built in PyTorch and trained on a single GeForce GTX 1080 GPU card with 12GB of available memory.
- All elements were run on CPUs only at test time (again determined by scheduler with no concern for CPU specifics).
- To process 10-minute recording: 214 seconds (12 seconds for SAD marks, 195 seconds for clustering, 7 seconds for resegmentation)